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What is claimed is:

1. A channel estimation method for a digital telecommunication station, comprising the steps of:

detecting a frequency correction burst by scanning of a wanted channel;

providing time and frequency synchronizations by using said frequency correction burst;

receiving a synchronization burst;

cross correlating received training sequence contained in said synchronous burst with a selected subset of an expected training sequence to obtain a channel estimate;

deriving a frequency error estimate from said channel estimate;

correcting the frequency error of the received

burst in accordance with said frequency error estimate;

equalizing the received synchronous burst; and

providing time and frequency synchronizations again

by using said corrected frequency correction burst.

2. A channel estimation method according to claim 1, wherein the received training sequence is part of the signal within a synchronization burst transmitted by a base station of a cellular telephone network.

- 3. A channel estimation method according to claim 2, wherein the received training sequence is the 64 bit training sequence of the GSM system.
- 4. A channel estimation method according to claim 3, wherein the selected subset comprises the 21st through to the 44th symbols of the training sequence.
- 5. A channel estimation method according to
  10 claim 1, wherein the training sequence is an adaptive
  training sequence.
- 6. A channel estimation method according to claim 2, wherein the training sequence is an adaptive training sequence.
  - 7. A channel estimation method according to claim 1, wherein the selected subset is an adaptive subset.

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- 8. A channel estimation method according to claim 2, wherein the selected subset is an adaptive subset.
- 9. A channel estimation method according to claim 6, wherein the selected subset is an adaptive

subset.

- 10. A channel estimation method according to claim 1, wherein the frequency error estimate is
  5 obtained by a Doppler tracking phase locked loop.
  - 11. A channel estimation method according to claim 2, wherein the frequency error estimate is obtained by a Doppler tracking phase locked loop.

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